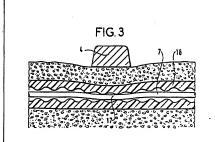
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  - GB 1497995 FR 2293709 A
  - FR 2280072 A
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# (54) A device for detecting the presence of an object

(57) A device for detecting the presence of an object. The device includes an optical fibre (7) which may be buried under e reilway line 4 to be monitored, a coherent light pulse generator which Injects a pulse into an and of the fibre, and a receiver which receives the pulse beckscattered by the fibre. The fibre 17 has a corrugated sheath 16 (16) which Intensifies the effect of local distortion on the fibre, thereby allowing measurement and detection of the position of the distortion of the fibre.



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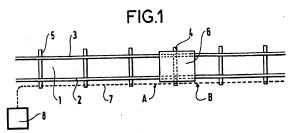


FIG.2

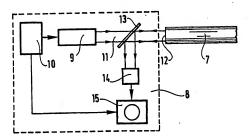
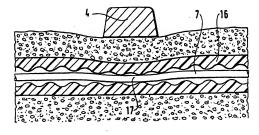
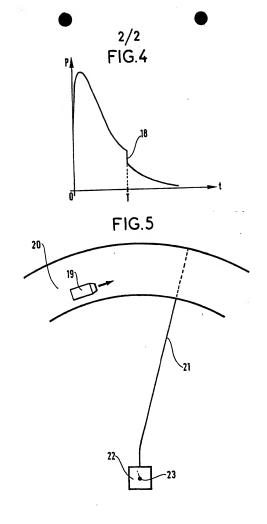


FIG.3





#### SPECIFICATION

10

# A device for detecting the presence of an object

5 The present invention relates to a device for detect-Ing the presence of en object, and it is particularly, but not exclusively adapted to detecting the position of an object along a line, e.g. a train along e reilwev.

### BACKGROUND TO THE INVENTION

British petent nº 1 497 995 describes a system for detecting the presence of an intruder around a per-15 Imeter which is being guarded. The system relies on the fact that imperfections in an optical fibre return echos of light pulses being transmitted by the fibre. The positions of the Imperfections can be deduced from their echos end echo-producing imperfec-

20 tions can be induced by a kink or bend in the fibre. Thue in the system described optical fibres ere laid around the perimeter and light pulses ere transmitted therein. When trodden on by en intruder the fibres return echos from the place where they ere 25 being distorted.

Unfortunately e usually desireable characteristic of optical fibres, namely their substantially interference - free transmission, is a hindrance in this particular application. The present invention therefore 30 alms at producing a device for detecting the presence of en object, in which the sensitivity of an optical fibre to local distortion caused by the object to be detected is increased with respect to that of conventional optical fibres. 35

# THE INVENTION

The present invention provides e device for detecting the presence of en object, the device, in-40 cluding:

- a light generator disposed at a reference point and capable of emitting an outgoing pulse; - an optical fibre disposed along a line in such a way that the weight of the object to be detected

45 when situeted near a portion of the fibre causes alestic distortion of the portion, one end of the fibre being placed so as to receive the outgoing pulse from the light generator, the distortion generating a return pulse by partial reflection; and

50 - a photoejectric receiver disposed near sald one end to receive the return pulse; wherein the optical fibre is surrounded by a covering which hes a rough inner surfece, seid distortion being exerted by the rough portions of the inner surface on the 55 outer surface of sald portion of the fibre.

### THE DRAWINGS

Two devices embodying the present invention 60 are described hereinbelow by way of exemple with reference to the accompanying drewings in which: - figure 1 shows schematically a first device embodying the invention;

- flaure 2 is a more detailed schematic Illustra-

part of the device illustrated in figure 1;

- figure 3 shows a partial cross-section of the device Illustrated in figure 1: - figure 4 is a graph of the signal which eppears

70 on e measuring device forming a part of the system lilustrated in figure 2; and

- figure 5 Illustrates schematically a second device ambodying the invention.

#### DESCRIPTION 75

Figure 1 shows a railwey track 1 which comprises two rails 2 and 3 fixed on sleepers such as 4 and 5 which rest on ballast. A vehicle 6, e.g. a locomotive,

80 travels along the track 1. An optical fibre 7 is disposed along the track 1. Preferably, the optical fibre 7 passes under the sleepers of the track, buried at a shallow depth in the ballast.

One end of the fibre 7 is connected to a light 85 transmitter-receiver system 8 placed at a reference point, e.g. in a station.

The trensmitter-receiver system 8 shown schematically in figure 2 includes a laser transmitter 9 such as an injection laser fed by a pulse generator

90 10. The light beam 11 emitted by the transmitter 9 is trained on the plane end surfeca 12 of the fibre 7 through a partially reflecting plate 13 inclined at 45° to the axis of the beam 11. A photoelectric receiver 14, constituted for example by a silicon diode, is

95 disposed to receive light coming from the fibre 7 and reflected by the plate 13. Electric pulses emitted by the receiver 14 are directed towards oscilloscope 15 whose scenning is synchronized with the frequency of the pulse generator 10.

100 Figure 3 shows a cross-section of the device Illustrated in figure 1, elong e plane AB perpendiculer to the plane of floure 1 and paratiel to the direction of the track 1. The plane cuts through one end of the sieeper 4 which is situated under the vehicle 6. The

105 plane also cuts through the ballast which supports the sleaper, so as to show the buried optical fibre 7. As shown in figure 3, the fibre 7 is surrounded by a covering 16 of plastics material. The inner surface of the covering 16 is rough end has, for example, 110 corrugations as shown in the figure.

The device described hereinabove operates as

follows. The weight of the vehicle causes a small temporery depression of the ballast, in particular under the 115 sleeper 4 which carries the weight of the vehicle 6. The deformation of the ballast, shown in an exeggerated illustration in figure 3, is transmitted to the covering 16 which segs in turn and causes elastic radial compression of the fibre 7 on a longitudinal

120 portion 17 situated immediately in the proximity of the point where the vahicle passes. By wey of an example, the longitudinal profile of the inner surfece of the covering 16 can have quasi-sinusoidal corrugations whose pitch is 2 millimetres and the

125 covering can communicate temporary axial deformations of about 100 to 200 microns to the outer surface of the fibre. The plestics material which constitutes the covering must be sufficiently hard to be able to obtain such deformations, but also

130 sufficantly soft to remain electic and not to breek

under the effect of the passage of the vehicle. The optical fibre is of the type used in optical telecommunications end can be mede of silica by the vapour phase dapoelting method, for example.

It is possible to detect the temporary deformation of the portion 17 of the fibre 7 by means of the transmitter-receiver system 8.

Indeed, the laser transmitter 9 injects recurrent outgoing light pulses into the fibre at a low rate. 10 The fibre does not transmit ell of the energy which it receives: eech point of the fibre returns a small portion of the input light energy to the end surface 12; this proportion depending on the coefficient of attanuation of the fibre. Figure 4 shows the graph 15 which appears on the screen of the oscilloscops 15 In response to en outgoing pulse emitted by the transmitter 9 and received on the receiver 14 after

beckscattering by the fibre 7.

The graph is plotted with two rectangular co20 ordinate axes OP and Ot, P on the Y-axis representing the back ecettered light power and I being time.
It is seen that generally, the curve decreases exponentially as a function of time. An irregularity is
observed on the curve, this irregularity is consti25 tuted by a return pulse 18 due to the local light

tuted by a return pulse 18 due to the local light ettenuation caused by the temporary deformation of the portion 17 of the fibre.

The intervel of time OT between the emission of the outgoing signal and the recaption of the return 30 algnal, read directly on the graph of figure 4, is proportional to the distance measured along the fibre? between the reference point and the point where the vehicle is pessing and therefore represents the position of the vehicle in relation to the 35 reference point.

The amplitude of the return signel 18 and the duration thereof also sllow the weight or the length of the vehicle to be estimated.

Figure 5 shows another embodiment of e device 40 In eccordance with the invention, seid embodiment being particularly suitable for detecting a vehicle 19 such as a roed vehicle driving along a road 20.

In this case, the device includes en optical fibre such as 21 a portion of which Is disposed across the 45 road 20, the fibre 21 being provided with a covering analogous to that described harainabove. It is preferantielly buried at a shallow depth in the ground, in particular where It crosses the road 20. One and of the fibre 21 reaches the input of a transmitter-for occlover system 22 situated at a reference point of and and analogous to that of the davice shown in figure

The operation of the device shown in figure 5, analogous to that of the davice shown in figure 1, 55 ellows the passage of the vehicle et a point of the road to be described without the vehicle driver being aware of the fact. Indeed, even in the case where the covering which surrounds the optical fibre is leid directly on the surface of the road, the covering 60 will be practally invisible if it is made of 6 translucent plastics material and here a small radius.

Tha device shown in figure 5 can be applied in particular to detecting the passage of a military vehicle on a road, the device placed at the refer-65 ance point then being suitably camouflaged. More particuarly, the device in accordence with the invention can be applied to detecting the presence of en object along e line. Since the optical fibre is disposed along the line, the possibly very light pressure exerted by the weight of the object et e point along the line makes it possible to determine the position of the object elong the line.

The object can be a person end the device can be applied for example to determining the errival of an 75 intruder inside civillan or military installations. In this case, it is difficult for the person whose presence is to be detected to know that he is being observed.

The object to be detected can also be a moving 80 body of any type, e.g. an eircraft taxling along a runwey, a truck or a cable car moving elong e teut cable.

### CLAIMS

- A device for detecting the presence of an object, the device, including:
- e light generator disposed at e reference point and capable of emitting an outgoing pulse;
- 90 en optical fibre disposed along a line, in such a way that the weight of the object to be datacted when situated near e portion of the fibre causes elastic distortion of the portion, one end of the fibre
- being pleced so ea to receive the outgoing pulse 95 from the light generator, the distortion generating e return pulse by partiel reflection; and
- a photoelectric receiver disposed near said one end to receive the return pulse; wherein the optical fibre is eurrounded by a covering which has a 100 rough inner surface, said distortion being exerted by the rough portions of the inner surface on the
- outer surface of sald portion of the fibre.

  2. A device according to cleim 1, wherein sald line is a railway track on sleepers, aald object is a 105 vehicle which travels along the track and the optical
  - fibre is pieced under the sleapers.

    3. A device eccording to claim 2, wharein the optical fibre is buried in the ballast of tha railway
- treck.

  4. A device eccording to cleim 1, wherein said line is disposed across a road, and said object is a vehicle moving elong the road.
- A davice according to claim 4, wherein the portion of the optical fibre which crosses the road is burled in the road.
  - A davice for detecting the presence of an object, substentially as herein described with reference to end as illustrated in figures 1 to 4 or figures 4 to 5 of the accompanying drawings.

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